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## THE HAHN-BANACH THEOREM FOR THE NORMED SPACES<sup>1</sup>

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## ABSTRACT

It is intended, in this chapter, to present the Hahn-Banach theorem in its version for the normed spaces. This result is particularly important in optimization problems because of the separation theorems consequences of it.

**Key words:** Hahn-Banach theorem, normed spaces, separation theorems

### **1. THE HAHN-BANACH THEOREM**

## 1.1. Convex Sets and Bodies

Be a real vector space L.

### Definition 1.1.1

A set  $K \subset L$  is **convex** if and only if

$$\begin{array}{c} \forall & \forall \\ x, y \in K \ \theta \in [0,1] \end{array} \theta x + (1 - \theta) y \in K \tag{1.1.1.} \blacksquare$$

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#### Definition 1.1.2

It is called **nucleus** of a set  $E \subset L$ , and designated J(E), the set of the points  $x \in E$  such that, given any  $y \in L$ , it is determined  $\varepsilon = \varepsilon(y) > 0$  such that  $x + ty \in E$  since  $|t| < \varepsilon$ .

## **Definition 1.1.3**

A convex set with non-empty nucleus is called convex body.

### Theorem 1.1.1

The nucleus of any convex set *K* is also convex.

#### Dem.:

Suppose that  $x, y \in J(K)$ . Be  $z = \theta x + (1 - \theta)y, 0 \le \theta \le 1$ . Then, given any  $a \in L$ , it is possible to determine  $\epsilon_1 > 0, \epsilon_2 > 0$  such that for  $|t_1| < \epsilon_1, |t_2| < \epsilon_2, x + t_1 a$  and  $x + t_2 a$  belong to K. So, the point  $\theta(x + ta) + (1 - \theta)(y + ta) = z + ta$  belongs to K for  $|t| < \epsilon = min\{\epsilon_1, \epsilon_2\}$  and  $z \in J(K)$ .

## Theorem 1.1.2

The intersection of any convex sets family is a convex set.

**Dem:** Be  $K = \bigcap_{\alpha}^{\bigcap} K_{\alpha}$ , where each  $K_{\alpha}$  is a convex set. Consider any two points *x* and *y* belonging to *K*. So  $\theta x + (1 - \theta)y, 0 \le \theta \le 1$  belongs to any  $K_{\alpha}$  and, in consequence, to *K*. Then *K* is convex.

### **Observation:**

-The intersection of convex sets, being a convex set, is not necessarily a convex body.

### **Definition 1.1.4**

Be *A* any part of a vector space *L*. Among the convex sets that contain *A* there is a minimal set: the intersection of the whole convex sets that contain  $A^2$ . This minimal convex set is called the **convex hull** of A.

#### 1.2. Homogeneous Convex Functionals Definition 1.2.1 A functional a defined in *L* is **convex** if and on

A functional *p* defined in *L* is **convex** if and only if

<sup>&</sup>lt;sup>2</sup> There is at least one convex set that contains A: the space L.

$$\forall \forall x, y \in L \ \theta \in [0,1] \ p(\theta x + (1-\theta)y) \le \theta p(x) + (1-\theta)p(y)$$
(1.2.1).

## Definition 1.2.2

A functional p is **positively homogeneous** if and only if

$$\begin{array}{c} \forall \quad \forall \\ x \in L \ \alpha > 0 \end{array} p(\alpha x) = \alpha p(x) \tag{1.2.2}. \blacksquare$$

### **Proposition 1.2.1**

For any convex positively homogeneous functional it always holds:

*i*) 
$$p(x + y) \le p(x) + p(y)$$
 (1.2.3)

$$ii) \ p(0) = 0 \tag{1.2.4},$$

iii) 
$$p(x) + p(-x) \ge 0, \quad \forall \\ x \in L$$
 (1.2.5),

$$iv) \ p(\alpha x) \ge \alpha p(x), \quad \forall$$
(1.2.6).

#### Dem:

i) In fact, 
$$p(x+y) = 2p\left(\frac{x+y}{2}\right) \le 2\left(p\left(\frac{x}{2}\right) + p\left(\frac{y}{2}\right)\right) = p(x) + p(y),$$

II) In fact, 
$$p(0) = p(\alpha 0) = \alpha p(0), \frac{1}{\alpha > 0}$$
. So  $p(0) = 0$ ,

iii) In this case, 
$$0 = p(0) = p(x + (-x)) \le p(x)p(-x)$$
,  $\nabla_{x \in I}$ 

*iv)* The result is evident for  $\alpha \ge 0$ . For  $\alpha < 0$ ,  $0 \le p(\alpha x) + p(-\alpha x) = p(\alpha x) + p(|\alpha|x) = p(\alpha x) + |\alpha|p(x)$ . That is:  $p(\alpha x) \ge \alpha p(x)$ .

## 1.3. Minkowsky Functionals

## Definition 1.3.1

Be *L* any vector space and *A* a convex body in *L* which nucleus contains 0. The *A* convex body Minkowsky functional, designated  $p_A(x)$ , is the functional

$$p_A(x) = \inf\left\{r: \frac{x}{r} \in A, r > 0\right\}$$
 (1.3.1).

### Theorem 1.3.1

A Minkowsky functional is convex, positively homogeneous and assumes only positive values. Reciprocally, if p(x) is a convex

positively homogeneous functional, assuming only positive values, and *k* appositive number, then the set

$$A = \{x : p(x) \le k\}$$
(1.3.2)

is a convex body with nucleus  $\{x: p(x) < k\}$ , which contains the point 0. If in (1.3.2) k = 1, the initial functional p(x) is the A Minkowsky functional.

**Dem:** Given any element  $x \in L$ ,  $\frac{x}{r}$  belongs to A if r is great enough. Then, the number  $p_A(x)$  defined by (1.3.1) is positive and finite.

But, given t > 0 and y = tx,  $p_A(y) = \inf\{r > 0: \frac{y}{r} \in A\} = \inf\{r > 0: \frac{tx}{r} \in A\} = \inf\{tr' > 0: \frac{x}{r'} \in A\} = t\inf\{tr' > 0: \frac{x}{r'} \in A\} = t\inf\{tr' > 0: \frac{x}{r'} \in A\} = tp_A(x).$ 

So,

$$p_A(tx) = t p_A(x), \begin{array}{c} \forall \\ t > 0 \end{array}$$
(1.3.3)

and  $p_A(x)$  is positively homogeneous.

Suppose now that  $x_1, x_2 \in L$ . Given any  $\epsilon > 0$ , choose the numbers  $r_i$  (i = 1,2) in the way that  $p_A(x_i) < r_i < p_A(x_i) + \epsilon$ . Then  $\frac{x_i}{r_i} \in A$ . Then, defining  $r = r_1 + r_2$ , the point  $\frac{x_1 + x_2}{r} = \frac{r_1}{rr_1} x_1 + \frac{r_2}{rr_2} x_2$  will belong to the set of points  $S = \left\{z: z = \theta \frac{x_1}{r_1} + (1-\theta) \frac{x_2}{r_2}, \theta \in [0,1]\right\}$ . As *A* is a convex set,  $S \subset A$  and, in particular,  $\frac{x_1 + x_2}{r} \in A$ . So,  $p_A(x_1 + x_2) \le r = r_1 + r_2 < p_A(x_1) + p_A(x_2) + 2\epsilon$ . As  $\epsilon$  is arbitrary,

$$p_A(x_1 + x_2) \le p_A(x_1) + p_A(x_2).$$
  
So,  $p_A(\theta x + (1 - \theta)y) \le p_A(\theta x) + p_A((1 - \theta)y) = \theta p_A(x) + (1 - \theta)$   
 $\forall \forall \forall \forall x = a \text{leady shown that}$ 

 $p_A(y), x, y \in L' \theta \in [0,1]$ , since it was already shown that  $p_A(x)$  is positively homogeneous.

Look now to the set defined by (1.3.2). If  $x, y \in A$  and  $\theta \in [0,1]$ , so  $p(\theta x + (1 - \theta)y) \le \theta p(x) + (1 - \theta)p(y) \le K$ . In consequence, *A* is a convex set. Suppose now that p(x) < K, t > 0 and  $y \in L$ . Under these conditions,  $p(x \pm ty) \le p(x) + tp(\pm y)$ . If p(-y) = p(y) =

0, so  $x \pm ty \in A$  for any t. If at least one of the numbers (positive) p(y), p(-y) is not null, so  $x \pm ty \in A$  for

$$t < \frac{K - p(x)}{\max\{p(y), p(-y)\}}.$$

From the definitions it results that p is the Minkowsky functional of the set  $\{x: p(x) \le 1\}$ .

## **Observation:**

-Taking in account the Theorem 1.3.1, the Minkowsky functional allows to establish a correspondence between the positively homogeneous convex functionals, assuming only positive values, and the convex bodies to which nucleus the origin belongs.

# 1.4. The Hahn-Banach-Theorem Definition 1.4.1

Consider a vector space L and its subspace  $L_0$ . Suppose that in  $L_0$  is defined a linear functional  $f_0$ . A linear functional *f* defined in the whole space L is an **extension** of the functional  $f_0$  if and only if

$$f(\mathbf{x}) = f_0(x), \begin{array}{c} \forall \\ x \in L_0. \end{array} \blacksquare$$

The Hahn-Banach theorem is essential in the in the resolution of the problem of finding an extension of a linear functional.

## Theorem 1.4.1 (Hahn-Banach)

Be *p* a positively homogeneous convex functional defined in a real vector space *L* and  $L_0$  an *L* subspace. If  $f_0$  is a linear functional defined in  $L_0$ , fulfilling the condition

$$f_0(x) \le p(x), \begin{array}{c} \forall \\ x \in L_0 \end{array}$$
(1.4.1),

so there is an extension *f* of  $f_0$  defined in *L*, linear, and such that  $f(x) \le p(x), \begin{array}{c} \forall \\ x \in L \end{array}$ .

#### Dem:

Begin showing that if  $L_0 \neq L$ , there is an extension of  $f_0$ , f', defined in a subspace L' such that  $L \subset L'$ , in order to fulfill the condition (1.4.1).

Be *z* any element of *L* not belonging to  $L_0$ ; if *L*'is the subspace generated by  $L_0$  and *z*, each element of *L*' is expressed in the form tz+x, being  $x \in L_0$ . If *f*'is an extension (linear) of the functional  $f_0$  to *L*', it will happen that  $f'(tz + x) = tf'(z) + f_0(x)$  or, making f'(z) = c,

$$f'(tz + x) = tc + f_0(x).$$

Now choose *c*, fulfilling the condition (5.1) in L', that is: in order that the inequality  $f_0(x) + tc \le p(x + tz)$ , for any  $x \in L_0$  and any real number *t*, is accomplished.

For t > 0 this inequality is equivalent to the condition  $f_0\left(\frac{x}{t}\right) + c \le p\left(\frac{x}{t} + z\right)$  or

$$c \le p\left(\frac{x}{t} + z\right) - f_0\left(\frac{x}{t}\right) \tag{1.4.2}.$$

For t < 0 it is equivalent to the condition  $f_0\left(\frac{x}{t}\right) + c \ge -p\left(-\frac{x}{t} - z\right)$ , or

$$c \ge -p\left(-\frac{x}{t}-z\right) - f_0\left(\frac{x}{t}\right) \tag{1.4.3}.$$

Now it will be proved that there is always a number *c* satisfying simultaneously the conditions (1.4.2) and (1.4.3).

Given any two elements y' and y'' belonging to  $L_0$ ,

$$-f_0(y'') + p(y'' + z) \ge -f_0(y') - p(-y' - z)$$
(1.4.4),

since  $f_0(y'') - f_0(y') \le p(y'' - y') = p((y'' + z) - (y' + z)) \le p(y'' + z) + p(-y' - z).$ 

Bec<sup>"</sup> =  $\inf_{y'} (-f_0(y'') + p(y'' + z))$  and  $c' = \sup_{y'} (-f_0(y') - p(-y' - z))$ . As y'and y" are arbitrary, it results from (1.4.4) that  $c'' \ge c'$ . Choosing c in order that  $c'' \ge c \ge c'$ , it is defined the functional f' on L' through the formula

$$f'(tz + x) = tc + f_0(x).$$

This functional satisfies the condition (1.4.1). So, any functional  $f_0$  defined in a subspace  $L_0 \subset L$  and subject in  $L_0$  to the condition (1.4.1), may be extended to a subspace L'. The extension f' satisfies the condition

$$f'(x) \le p(x), \stackrel{\forall}{x \in L'}$$

If *L* has an algebraic numerable base  $(x_1, x_2, ..., x_n, ...)$  the functional in *L* is built by finite induction, considering the increasing sequence of subspaces

$$L^{(1)} = (L_0, x_1), L^{(2)} = (L^{(1)}, x_2), \dots$$

designating  $(L^{(k)}, x_{k+1})$  the *L* subspace generated by  $L^{(k)}$  and  $x_{k+1}$ . In the general case, that is, when *L* has not an algebraic numerable base, it is mandatory to use a **transfinite induction** process, for instance the Haudsdorf maximal chain theorem.

Call  $\mathcal{F}$  the set of the whole pairs(L', f'), at which L' is a L subspace that contains  $L_0$  and f' is an extension of  $f_0$  to L' that fulfills (1.4.1). Order partially  $\mathcal{F}$  so that

$$(L', f') \le (L'', f'')$$
 if and only if  $L' \subset L''$  and  $f''_{|L'} = f'$ .

By the Haudsdorf maximal chain theorem, there is a **chain**, that is: a subset of  $\mathcal{F}$  totally ordered, **maximal**, that is: not strictly contained in another chain. Call it  $\Omega$ . Be  $\Phi$  the family of the whole L'such that  $(L', f') \in \Omega$ .  $\Phi$  is totally ordered by the sets inclusion; so, the union T of the whole elements of  $\Phi$  is a *L* subspace. If  $x \in T$ then  $x \in L'$  for some  $L' \in \Phi$ ; define  $\tilde{f}(x) = f'(x)$ , where f' is the extension of  $f_0$  that is in the pair (L', f')- the definition of  $\tilde{f}$  is obviously coherent. It is easy to check that T = L and that f = f'satisfies the condition (1.4.1).

Now the Hahn-Banach theorem complex case, corresponding to the contribution of Hahn to the theorem, will be presented. But first:

#### **Definition 1.4.2**

A linear functional *p*, assuming only positive values, defined in a complex vector space *L*, is homogeneous convex if and only if, for any  $x, y \in L$  and any complex number  $\lambda$ ,

$$p(x + y) \le p(x) + p(y),$$
$$p(\lambda x) = |\lambda| p(x). \blacksquare$$

## Theorem 1.4.1a (Hahn-Banach)

Be *p* an homogeneous convex functional defined in a vector space *L* and  $f_0$  a linear functional, defined in a subspace  $L_0 \subset L$ , fulfilling the condition

$$|f_0(x)| \le p(x), x \in L_0.$$

Then, there is a linear functional f defined in L, satisfying the conditions

$$|f(x)| \le p(x), x \in L; f(x) = f_0(x), x \in L_0.$$

#### Dem:

Call  $L_R$  and  $L_{0R}$  the real vector spaces underlying, respectively, the spaces L and  $L_0$ . As it is evident, p is an homogeneous convex functional in  $L_R$  and  $f_{0R}(x) = Ref_0(x)$  a real linear functional in  $L_{0R}$  fulfilling the condition  $|f_{0R}(x)| \le p(x)$  and so,

$$f_{0R}\left(x\right) \le p(x).$$

Then, owing to Theorem 1.4.1, there is a real linear functional  $f_R$ , defined in the whole  $L_R$  space, that satisfies the conditions

$$f_R(x) \le p(x), x \in L_R; f_R(x) = f_{0R}(x), x \in L_{0R}.$$

But,  $-f_R(x) = f_R(-x) \le p(-x) = p(x)$ , and  $|f_R(x)| \le p(x), x \in L_R$  (1.4.5). Define in *L* the functional *f* making

$$f(x) = f_R(x) - if_R(ix).$$

It is immediate that *f* is a complex linear functional in *L* such that

 $f(x) = f_0(x), x \in L_0; Ref(x) = f_R(x), x \in L.$ 

It only misses to show that  $|f(x)| \le p(x), \ \substack{\forall \\ x \in L}$ .

Proceed by absurd. Suppose that there is  $x_0 \in L$  such that  $|f(x_0)| > p(x_0)$ . So,  $f(x_0) = \rho e^{i\varphi}$ ,  $\rho > 0$ , and making  $y_0 = e^{-i\varphi}x_0$ , it would happen that  $f_R(y_0) = Re[e^{-i\varphi}f(x_0)] = \rho > p(x_0) = p(y_0)$  that is contrary to (1.4.5).

## 2. THE HAHN-BANACH-THEOREM FOR THE NORMED SPACES

## 2.1. Normed Spaces

## Definition 2.1.1

Calling *L* a vector space, a **norm** in *L* is a functional *p* such that:

 $-p(x) \ge 0$ , -p(x) = 0 if and only if x = 0,  $-p(x + y) \le p(x) + p(y)$ ,  $-p(\alpha x) = |\alpha|p(x)$ , for every  $\alpha$ .

A vector space *L* with a norm is a **normed space**. It is usual to designate the norm of an element  $x \in L$ , ||x||.

Every normed space is a metric space, with the distance

$$d(x, y) = ||x - y||.$$

## 2.2. Continuous Linear Functionals

Be *E* a normed vector space.

## **Definition 2.2.1**

A linear functional *f*, defined in *E*, is continuous in  $x_0 \in E$  if and only if, for any  $\varepsilon < 0$ , there is a neighboring *U* of  $x_0$  such that

$$|f(x) - f(x_0)| < \varepsilon$$
 for  $x \in U$ .

#### **Definition 2.2.2**

A linear functional *f*, defined in *E*, is continuous if it is continuous in all  $x_0 \in E$ .

Follow some important results on the continuity of linear functionals defined in normed vector spaces.

## Proposition 2.2.1

Be *E* a normed vector space and *f* a linear functional in *E*. So

*i*) If *E* has finite dimension, *f* is continuous,

*ii) f* is continuous if and only if *f* is continuous at the origin,

iii) f is continuous if and only if f is bounded over the unitary ball.

## **Definition 2.2.3**

Be *f* a continuous linear functional in a normed space *E*. It is called *f* **norm**, and designated ||f||,

$$||f|| = \sup_{||x|| \le 1} |f(x)|$$

that is: the supreme of the values that |f(x)| assumes in the *E* unitary ball.

## **Observation:**

-The class of continuous linear functionals so defined, is a vector normed space, called the *E* dual space, designated E'.

## 2.3. The Hahn-Banach Theorem Version in Normed Spaces

The Theorem 1.4.1 is as follows, in normed spaces:

## Theorem 2.3.1 (Hahn-Banach)

Name *L* a subspace of a real normed space *E* and  $f_0$  a bounded linear functional in L. So, there is a linear functional defined in *E*, extension of  $f_0$ , such that

$$\|f_0\|_{L'} = \|f\|_{E'}.$$

### Dem:

It is enough to think in the functional K||x|| at which  $K = ||f_0||_{L^1}$ . As it is convex and positively homogeneous, it is possible to put p(x) = K||x|| and to apply Theorem 1.4.1.

## **Observation:**

- To see an interesting geometric interpretation of this theorem, consider the equation  $||f_0(x)|| = 1$ . It defines, in *L*, an hiperplane at distance  $\frac{1}{||f_0||}$  of 0. Considering the extension *f* of  $f_0$ , with norm conservation, it is obtained an hiperplane in *E*, that contains the hiperplane considered behind in *L*, and that at the same distance from the origin.

The version for normed spaces of Theorem 1.4.1a is:

## Theorem 2.3.1a (Hahn-Banach)

Be E a complex normed space and  $f_0$  a bounded linear functional defined in a subspace  $L \subset E$ . So, there is a bounded linear functional *f*, defined in *E*, such that

$$f(x) = f_0(x), x \in L; ||f||_{E'} = ||f_0||_{L'}.$$

## 2.4. Separation Theorems

In this this section, two separation theorems, important consequences of the Hahn-Banach theorem, applied to the normed vector spaces, will be presented.

### **Observation:**

- It was seen that a convex body, in a vector space, is a convex set with non-empty nucleus. It may be stated that:

*i*) In a normed space, the nucleus of a set is coincident with the total of its interior points, and so

*ii)* In a normed space, a convex body is a convex set the has, at least, one interior point.

## Theorem 2.4.1 (Separation)

Consider two convex sets *A* and *B* in a normed space *E*. If one of them, for instance *A*, has at least on interior point and  $(intA) \cap B = \emptyset$ , there is a continuous linear functional non-null that separates the sets *A* and *B*.

## Theorem 2.4.2 (Separation)

Consider a closed convex set *A*, in a normed space *E*, and a point  $x_0 \in E$ , not belonging to *A*. So, there is a continuous linear functional, non-null, that separates strictly  $\{x_0\}$  and A.

## 3. CONCLUSIONS

After a review on convex sets and bodies, homogeneous convex functionals, Minkowsky functionals and continuous convex functionals, the Hahn-Banach theorem for the normed spaces is presented, of course base on its general version. In addition two important separation theorems consequences of the Hahn-Banach theorem for the normed spaces are enounced. These last results are important in the optimization of functionals.

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