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Convex Sets Strict Separation

in the Minimax Theorem

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Abstract

The convex sets strict separation is very useful to obtain mathematical optimization results. The minimax theorem, a key result in Game Theory is an example. It will be outlined in this work.

Keywords: Minimax theorem, game theory, convex sets

1 Introduction

Be a zero-sum two players game. Call W the winner player and L the loser player. The payoff table when W chooses the strategy i, i = 1, 2, ..., m and L chooses the strategy j, j = 1, 2, ..., n is

> Player \boldsymbol{L} Player \boldsymbol{W} $\begin{bmatrix} g_{ij} \end{bmatrix}$ i = 1, 2, ..., m and j = 1, 2, ..., n

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reading the player W the values as earnings and the player L as losses. Evidently, a negative earning is a loss and vice-versa. In terms of von Neumann's minimax theorem [2], the problem may be solved as a linear programming problem, see for instance [3]:

For player W

the target is to maximize G_w , the value of the game, subject to the constraints $\sum_{i=1}^{m} g_{ij} x_i \ge G_w$, j = 1, 2, ..., n, $\sum_{i=1}^{m} x_i = 1, x_i \ge 0$, i = 1, 2, ..., m, being x_i the frequency at which the player chooses its *i* strategy, i = 1, 2, ..., m.

For player L

the target is to minimize G_L , the value of the game, subject to the constraints $\sum_{j=1}^n g_{ij} y_j \ge G_L$, i = 1, 2, ..., m, $\sum_{j=1}^n y_j = 1, y_j \ge 0$, j = 1, 2, ..., n, being y_j the frequency at which the player chooses its *j* strategy, j = 1, 2, ..., n.

Whenever there is a solution $G_w = G_L$. If $\max_i \min_j g_{ij} = \min_j \max_i g_{ij}$, i = 1, 2, ..., m; j = 1, 2, ..., n the common value is the game value and the mathematical programs² presented above are not useful. Note that in this kind of problems there is a maximization of minimums and a minimization of maximums.

In order to present a mathematical basis for this tool, it will be seen how the convex sets strict separation allows obtaining this key result in game theory.

Consider then the zero-sum two players games formulation:

-Be $\phi(x, y)$ a real function of two real variables $x, y \in H$ (real Hilbert space). -Be *A* and *B* two convex sets in *H*.

-One of the players chooses strategies (points) in A, in order to maximize $\phi(x, y)$ (or to minimize $(-1)\phi(x, y)$): it is the maximizing player.

- The other player chooses strategies (points) in *B*, in order to minimize $\phi(x, y)$ (or to maximize $(-1)\phi(x, y)$): it is the minimizing player.

 $-\phi(x, y)$ is the payoff function. $\phi(x_0, y_0)$ represents, simultaneously, the maximizing player earning and the minimizing player loss in a move at which they chose, respectively, the strategies x_0 and y_0 .

This game has value G if

$$\sup_{x \in A} \inf_{y \in B} \phi(x, y) = G = \inf_{y \in B} \sup_{x \in A} \phi(x, y) \quad (1.1).$$

If for any (x_0, y_0) , $\phi(x_0, y_0) = G$, (x_0, y_0) is a pair of optimal strategies. It is also a saddle point if

$$\phi(x, y_0) \le \phi(x_0, y_0) \le \phi(x_0, y), x \in A, y \in B$$
(1.2).

²Note that these two programs are duals of each other.

2 Strict Separation

The Banach-Sachs theorem, see for instance [5], is very important for the sequence of this work:

Theorem 2.1 (Banach-Saks)

Suppose that x_n converges weakly to x. So it is possible to determine a subsequence $\{x_{n_k}\}$, such that the arithmetical means $\frac{1}{m}\sum_{k=1}^m x_{n_k}$ converge to x.

Observation:

-An alternative formulation of this theorem is: A closed convex subset is weakly closed.

And also, see again [5], the

Theorem 2.2 (Convex functionals weak inferior semi continuity)

Be $f(\cdot)$ a continuous convex functional in Hilbert space *H*. So if x_n converges weakly to $x, \underline{lim} f(x_n) \ge f(x)$.

Theorem 2.3

Consider *A* and *B* closed convex sets in *H*, with *A* bounded. Be $\phi(x, y)$ a real functional defined for *x* in *A* and *y* in B such that:

 $-\phi(x,(1-\theta)y_1+\theta y_2) \le (1-\theta)\phi(x,y_1)+\theta\phi(x,y_2) \text{ for } x \text{ in } A \text{ and}$ $y_1, y_2 \text{ in } B, 0 \le \theta \le 1,$

$$-\phi((1-\theta)x_1+\theta x_2, y) \ge (1-\theta)\phi(x_1, y) + \theta\phi(x_2, y) \text{ for } y \text{ in } B \text{ and}$$
$$x_1, x \text{ in } A, 0 \le \theta \le 1,$$

- $\phi(x, y)$ is continuous in *x* for each *y*,

then (1.1) is fulfilled, that is : the game has a value.

Proof: Obviously $\inf_{y \in B} \phi(x, y) \leq \phi(x, y) \leq \sup_{x \in A} \phi(x, y)$ and so $\sup_{x \in A} \inf_{y \in B} \phi(x, y) \leq \inf_{y \in B} \sup_{x \in A} \phi(x, y)$. Then as $\phi(x, y)$ is concave and continuous in $x \in A$, A convex, closed and bounded, it follows that G = $\inf_{y \in B} \sup_{x \in A} \phi(x, y)$. Suppose now that there is $x_0 \in A$ such that $\phi(x_0, y) \geq G$, for each y in B. If this is the case, $\inf_{y \in B} \phi(x_0, y) \geq G$ or $\sup_{x \in A} \inf_{y \in B} \phi(x, y) \geq G$ as it is convenient. So, in the sequence it will be demonstrated the existence of such $a x_0$.

For each y in B, call $A_y = \{x \in A : \phi(x_0, y) \ge G\}$. A is closed, bounded and convex. Suppose that, for a finite set $\{y_1, y_2, ..., y_n\}$, $\bigcap_{i=1}^n A_{y_i} = \emptyset$. Consider the transformation from A to E_n defined by $f(x) = (\phi(x, y_1) - G, \phi(x, y_2) - G, ..., \phi(x, y_2) - G)$. Call F the f(A) set convex hull closure. Be \mathscr{P} the closed positive cone in E_n . $\mathscr{P} \cap F = \emptyset$: in fact, being $\phi(x, y)$ concave in x, for any x_k in $k = 1, 2, ..., n, 0 \le \theta \le 1, \sum_{k=1}^n \theta_k = 1, \sum_{k=1}^n \theta_k(\phi(x_k, y) - G) \le 0$

 $\phi(\sum_{k=1}^{n} \theta_k x_k; y) - G$ and so the f(A) convex extension does not intersect \wp . Consider now a sequence x_n in A, such that $f(x_n)$ converges to $v, v \in E_n$. As Ais closed, bounded and convex, it is possible to find a subsequence, designated $\{x_m\}$, convergent for an element of A (call it x_0). Moreover, for any y_i , as $\phi(x, y_i)$ is concave in x, $\overline{lim}\phi(x_m, y_i) \leq \phi(x_0, y_i)$, that is $f(x_0) \geq \overline{lim}f(x_m) = v$. So $F \cap \wp = \emptyset$. Then F and \wp may be strictly separated, and it is possible to find a vector in E_n with components a_k , fulfilling $\sup_{x \in A} \sum_{i=1}^{n} a_i (\phi(x, y_i) - G) < \sum_{i=1}^{n} a_i \rho_i, \text{ with the whole } a_i \text{ great or equal than}$ zero. Obviously, the whole a_i must be non-negative, not being possible to have the whole of them simultaneously null. So, dividing by $\sum_{i=1}^{n} a_i$, as $\phi(x, y)$ is convex in y, an making the whole ρ_i zero, $\sup_{x \in A} \phi(x, \bar{y}) - G < 0$, with $\bar{y} = \frac{\sum_{i=1}^{n} a_k y_k}{\sum_{i=1}^{n} a_k}$. And $\bar{y} \in B$ that is $\inf_{y \in B} \sup_{x \in A} \phi(x, y) < G$, what is contradictory with the definition of G. So, $\bigcap_{i=1}^{n} A_{y_i} \neq \phi$.

Now it will be shown that, in fact, $\stackrel{\bigcap}{y \in B} A_y \neq \emptyset$, using that result and proceeding by absurd. Note that A_y is closed and convex. So, by Theorem 2.1, is also weakly closed, and, as it is bounded, is compact in the weak topology such as A. Call D_y the A_y complementary. D_y is open in the weak topology. So, if $y \in B A_y$ is empty, $\stackrel{\bigcup}{y \in B} D_y \supset H \supset A$. But, being A compact, it is known that a finite number of D_{y_i} is enough to cover A: $\bigcup_{i=1}^m D_{y_i} \supset A$, that is $\bigcup_{i=1}^m A_{y_i}$ is contained in the complementary of A and it must be $\bigcap_{i=1}^n A_{y_i} = \emptyset$, leading to a contradiction.

So suppose that $x_0 \in \bigcap_{y \in B}^{\cap} A_y$, then x_0 satisfies $\phi(x_0, y) \ge G$, as wished.

3 The Minimax Theorem

The minimax theorem is obtained as a corollary of Theorem 2.3 strengthening its hypothesis. Now it is important to the sequence the following result:

Theorem 3.1

A continuous convex functional in a Hilbert space has minimum in any closed and bounded convex set.

Proof: In a space with finite dimension, obviously the set convexity is not needed. In spaces with infinite dimension, note that if x_n is a minimizing sequence, so, as the sequence is bounded, it is admissible to work with a weakly convergent sequence and, by Theorem 2.2, there is weak inferior semi continuity: $\underline{lim} f(x_n) \ge f(x)$, designating $f(\cdot)$ the functional, where x is the weak limit, and so the minimum is f(x). As a closed convex set is weakly closed, x belongs to the closed convex set.

Theorem 3.2 (Minimax)

Suppose that the Theorem 2.3 functional $\phi(x, y)$ is continuous in both variables, separately, and is also bounded. Then there is an optimal pair of strategies fulfilling the property of being a saddle point.

Proof: It was seen that there is x_0 satisfying $\phi(x_0, y) \ge G$ for each y. As $\phi(x_0, y)$ is continuous in y and B is bounded, $\inf_{y \in B} \phi(x_0, y) = \phi(x_0, y_0) \ge G$, for some y_0 in B, by Theorem 3.1. But $\inf_{y \in B} \phi(x_0, y) \le \sup_{x \in A} \inf_{y \in B} \phi(x, y) = G$ and so $\phi(x_0, y_0) = G$. The saddle point property follows trivially from the above arguments.

4 Conclusions

The separation concept, see [4], is very important to establish rigorously the Mathematical Convex Programing results, as it was exemplified in this work with the minimax theorem. The Khun-Tucker theorem and the Nash equilibrium are other very interesting examples, see [3] and [6]. Note finally the important role played by the weak convergence in Hilbert spaces concept in the demonstrations presented.

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