

Repositório ISCTE-IUL

Deposited in *Repositório ISCTE-IUL*:

2024-09-10

Deposited version:

Accepted Version

Peer-review status of attached file:

Peer-reviewed

Citation for published item:

Carvalho, L., Diogo, C., Mendes, S. & Soares, H. (2024). A note on the essential numerical range of block diagonal operators. *Forum Mathematicum*. 36 (5), 1147-1157

Further information on publisher's website:

10.1515/forum-2023-0166

Publisher's copyright statement:

This is the peer reviewed version of the following article: Carvalho, L., Diogo, C., Mendes, S. & Soares, H. (2024). A note on the essential numerical range of block diagonal operators. *Forum Mathematicum*. 36 (5), 1147-1157, which has been published in final form at <https://dx.doi.org/10.1515/forum-2023-0166>. This article may be used for non-commercial purposes in accordance with the Publisher's Terms and Conditions for self-archiving.

Use policy

Creative Commons CC BY 4.0

The full-text may be used and/or reproduced, and given to third parties in any format or medium, without prior permission or charge, for personal research or study, educational, or not-for-profit purposes provided that:

- a full bibliographic reference is made to the original source
- a link is made to the metadata record in the Repository
- the full-text is not changed in any way

The full-text must not be sold in any format or medium without the formal permission of the copyright holders.

A NOTE ON THE ESSENTIAL NUMERICAL RANGE OF BLOCK DIAGONAL OPERATORS

LUÍS CARVALHO, CRISTINA DIOGO, SÉRGIO MENDES, AND HELENA SOARES

ABSTRACT. In this note we characterize the essential numerical range of a block diagonal operator $T = \bigoplus_i T_i$ in terms of the numerical ranges $\{W(T_i)\}_i$ of its components. Specifically, the essential numerical range of T is the convex hull of the limit superior of $\{W(T_i)\}_i$. This characterization can be simplified further. In fact, we prove the existence of a decomposition of T for which the convex hull is not required.

INTRODUCTION

Block diagonal operators are a generalization of diagonal operators, hence it is not surprising that many properties of the former are emulated from the latter. An example is the numerical range $W(T_\oplus) = \text{conv}(\{W(T_n)\}_n)$ of a block diagonal operator $T_\oplus = \bigoplus_n T_n$, which can be seen as generalizing the formula of the numerical range of a diagonal operator $D = \text{diag}((\lambda_n)_n)$ given by $W(D) = \text{conv}(\{\lambda_n\}_n)$. That is,

$$W(D) = \text{conv}(\{\lambda_n\}_n) \text{ and } W(T_\oplus) = \text{conv}(\{W(T_n)\}_n).$$

In the same vein, one can ask whether $W_e(T_\oplus)$, the essential numerical range of a block diagonal operator T_\oplus , maintains the analogy with $W_e(D)$, the essential numerical range of a diagonal operator D .

Furthermore, one can also ask, since block diagonal operators are defined with respect to a decomposition, which of such properties are independent from the choice of the decomposition.

This note is about the pursuit of the analogy referred above and provides two descriptions of the essential numerical range: one that is independent of the choice of the decomposition (see Theorem 3) and another one, simpler, that it is not (Proposition 8).

To compute the essential numerical range when $T_\oplus = \bigoplus_n T_n$ is a block diagonal operator, we are led to consider the limit superior of a sequence of sets. However, a slight adaptation is required since the essential numerical range is a convex and closed set. Thus, the main result of the paper is Theorem 3, which states that for any decomposition the essential numerical range

Date: November 30, 2023.

2010 Mathematics Subject Classification. 47A12.

Key words and phrases. Block diagonal operator, essential numerical range.

The first and second authors were partially supported by FCT through CAMGSD, project UID/MAT/04459/2019. The third author was partially supported by FCT through CMA-UBI, project UIDB/00212/2020. The fourth author was partially supported by FCT through CIMA, project UIDB/04674/2020.

of a block diagonal operator $T_\oplus = \bigoplus_n T_n$ is given by

$$W_e(T_\oplus) = \text{conv} \left(\bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(T_n)} \right) = \text{conv} \left(\overline{\lim} W(T_n) \right), \quad (1)$$

where we use the (closed) limit superior of a sequence of sets X_n , $n \in \mathbb{N}$, as $\overline{\lim} X_n = \bigcap_k \overline{\bigcup_{n \geq k} X_n}$. On the other hand, the essential numerical range of a diagonal operator $D = \text{diag}((\lambda_n)_n)$ is the closed and convex set generated by $\overline{\lim} \{\lambda_n\}$, the set of the limit points of the diagonal, i.e. $W_e(D) = \text{conv} \left(\overline{\lim} \{\lambda_n\} \right)$.

In this way, we recover the analogy from the numerical range of a diagonal and a block diagonal operator. In particular, the essential numerical range of a diagonal operator is a special instance of the block diagonal case. We deduce from (1) that

$$W_e(D) = \text{conv} \left(\overline{\lim} \{\lambda_n\} \right) \quad \text{and} \quad W_e(T_\oplus) = \text{conv} \left(\overline{\lim} W(T_n) \right).$$

Regarding the existence of a decomposition $T_\oplus = \bigoplus_n \tilde{T}_n$ where the convex hull is not required, we prove:

$$W_e(T) = \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(\tilde{T}_n)}.$$

We remark that throughout the text, when we refer to limit superior we always mean the closed limit superior as above and not the usual definition.

We now recall some terminology and fix the notation used throughout the text.

Let \mathcal{H} be a complex separable Hilbert space with inner product $\langle \cdot, \cdot \rangle$. Denote $\mathbb{S}_{\mathcal{H}} = \{x \in \mathcal{H} : \langle x, x \rangle = \|x\|^2 = 1\}$ the unit sphere in \mathcal{H} . As usual, $\mathcal{B}(\mathcal{H})$ denotes the algebra of bounded linear operators on \mathcal{H} and $\mathcal{K}(\mathcal{H})$ its closed ideal of compact operators.

The numerical range of an operator $T \in \mathcal{B}(\mathcal{H})$ is the set

$$W(T) = \{\langle Tx, x \rangle : x \in \mathbb{S}_{\mathcal{H}}\} \subset \mathbb{C},$$

and the essential numerical range of T is defined by

$$W_e(T) = \bigcap_{K \in \mathcal{K}(\mathcal{H})} \overline{W(T + K)}.$$

It is well known that $W_e(T) \subseteq \overline{W(T)}$, see [FSW].

Now we introduce the notion of essential sequence. As usual, we write $x_n \rightharpoonup x$ if a sequence $(x_n)_n$ in \mathcal{H} converges to $x \in \mathcal{H}$ in the weak topology.

Definition 1. An essential sequence $(x_n)_n \subset \mathcal{H}$ for $\omega \in \mathbb{C}$ is a sequence of unit vectors such that $x_n \rightharpoonup 0$ and $\langle Tx_n, x_n \rangle \rightarrow \omega$.

The existence of an essential sequence for an element $\omega \in \mathbb{C}$ is a necessary and sufficient condition for ω be in $W_e(T)$ (see [FSW, Corollary in page 189]).

We will be especially dealing with convex sets, so it is useful to introduce the simplex of the space of sequences $\ell^2(\mathbb{R})$, that is $\Delta_{\ell^2(\mathbb{R})} = \{(a_n)_n \in \ell^2(\mathbb{R}) : \sum_{n \geq 1} a_n = 1, a_n \geq 0\}$. Furthermore, the notion of extreme point will also be important. A point $z \in W(T)$ is called an extreme point if, given a convex combination $z = \alpha z_1 + (1 - \alpha) z_2$, with $\alpha \in (0, 1)$ and $z_1, z_2 \in W(T)$, then necessarily $z = z_1 = z_2$.

Although it is folklore knowledge, we introduce a detailed account on block diagonal operators (which is usually overlooked) to facilitate the proofs. Set $(t_n)_n$ to be an increasing sequence of non-negative integers, with $t_0 = 0$, and $\ell_n = t_n - t_{n-1}$ for positive integers. **Fix the canonical bases $\mathcal{E}_n = \{e_i^{(n)} : 1 \leq i \leq \ell_n\}$ for \mathbb{C}^{ℓ_n} , for all $n \in \mathbb{N}$.** Let $(A_n)_n$ be a sequence of matrices, where each matrix $A_n \in \mathcal{M}_{\ell_n}(\mathbb{C})$ is defined with respect to the basis $\mathcal{E}_n \subset \mathbb{C}^{\ell_n}$ so that its entries are given by

$$a_{ij}^{(n)} = \langle A_n e_j^{(n)}, e_i^{(n)} \rangle,$$

for $1 \leq i, j \leq \ell_n$.

Fix an orthonormal Hilbert basis $\mathcal{B} = \{u_n : n \in \mathbb{N}\}$ for \mathcal{H} . The elements of \mathcal{B} may be assembled as

$$\mathcal{B} = \underbrace{\{u_1, \dots, u_{t_1}\}}_{\mathcal{B}_1} \underbrace{\{u_{t_1+1}, \dots, u_{t_2}\}}_{\mathcal{B}_2} \dots \underbrace{\{u_{t_{n-1}+1}, \dots, u_{t_n}\}}_{\mathcal{B}_n} \dots.$$

That is, $\mathcal{B} = \bigcup_{n \geq 1} \mathcal{B}_n$, where $\mathcal{B}_n = \{u_i^{(n)} = u_{t_{n-1}+i} : 1 \leq i \leq \ell_n\}$. According to this decomposition, \mathcal{H} is the direct sum of finite dimensional orthogonal Hilbert (sub)spaces $\mathcal{H}_n := \text{span } \mathcal{B}_n$ of \mathcal{H} and we have $\mathcal{H} = \bigoplus_{n \geq 1} \mathcal{H}_n$. In particular, $x \in \mathcal{H}$ if and only if $x = (x_n)_n$, with $x_n \in \mathcal{H}_n$ and $\sum_{n \geq 1} \|x_n\|^2 < \infty$. The inner product is $\langle x, y \rangle = \sum_{n \geq 1} \langle x_n, y_n \rangle_{\mathcal{H}_n}$, where $x = (x_n)_n$, $y = (y_n)_n$ with $x_n, y_n \in \mathcal{H}_n$.

Taking into account this decomposition, a block diagonal bounded operator $T : \mathcal{H} \rightarrow \mathcal{H}$ (with respect to the decomposition $\mathcal{H} = \bigoplus_{n \geq 1} \mathcal{H}_n$) can be defined as follows. For each $n \in \mathbb{N}$, let $T_n : \mathcal{H}_n \rightarrow \mathcal{H}_n$ be the bounded operator given by

$$T_n(u_i^{(n)}) = (\phi_n A_n \phi_n^{-1})(u_i^{(n)}), \quad \forall i = 1, \dots, \ell_n,$$

where $\phi_n : \mathbb{C}^{\ell_n} \rightarrow \mathcal{H}_n$ is an isometry of Hilbert spaces defined by

$$\phi_n(e_i^{(n)}) = u_i^{(n)}.$$

Now define

$$T = \bigoplus_{n \geq 1} T_n : \mathcal{H} \rightarrow \mathcal{H}$$

$$x \mapsto T(x) = T((x_n)_n) = (T_n(x_n))_n.$$

We note that for T to be bounded it is necessary and sufficient that $\|T\| = \sup_n \|T_n\| < \infty$. Moreover, we have

$$\langle Tx, x \rangle = \sum_n \langle Tx_n, x_n \rangle = \sum_n \langle T_n x_n, x_n \rangle = \sum_n \langle A_n \phi_n^{-1} x_n, \phi_n^{-1} x_n \rangle.$$

According to the above construction, from now on, by abuse of notation, we will write $T = \bigoplus A_n$.

The construction of a block diagonal operator $T = \bigoplus_n A_n$ depends on the fixed decomposition $\mathcal{H} = \bigoplus \mathcal{H}_n$ (and on the operators $A_n : \mathcal{H}_n \rightarrow \mathcal{H}_n$). Obviously, this decomposition may not be unique since it may exist some other decomposition, $\mathcal{H} = \bigoplus_n \tilde{\mathcal{H}}_n$, giving rise to a new block diagonal decomposition $T = \bigoplus_n \tilde{A}_n$, where $\tilde{A}_n : \tilde{\mathcal{H}}_n \rightarrow \tilde{\mathcal{H}}_n$. A natural question is for which decompositions of T is the computation of the essential numerical range simpler. Proposition 8 provides a partial answer to this question for it provides, as already mentioned, a decomposition for which the convex hull in equation (1) can be discarded.

ESSENTIAL NUMERICAL RANGE

Our main result states that the essential numerical range of T is the convex hull of the set $\bigcap_{k=1}^{\infty} \overline{\bigcup_{n \geq k} W(A_n)}$, i.e. it is the (closed) convex hull of the limit superior of the sets $W(A_n)$, for all n . To prove it, we need the following lemma.

Lemma 2. *Let $S_k \subset \mathbb{C}$, for any $k \in \mathbb{N}$. If S_k is a decreasing sequence of compact sets, then*

$$\bigcap_{k \geq 1} \text{conv}(S_k) = \text{conv}\left(\bigcap_{k \geq 1} S_k\right).$$

Proof. Since $\bigcap_{k \geq 1} S_k \subseteq S_j$, it follows that $\text{conv}(\bigcap_{k \geq 1} S_k) \subseteq \text{conv}(S_j)$, for any j . It follows that $\text{conv}(\bigcap_{k \geq 1} S_k) \subseteq \bigcap_{j \geq 1} \text{conv}(S_j)$.

For the reverse inclusion we use Carathéodory's Theorem. More precisely, since $\mathbb{C} \cong \mathbb{R}^2$, any $s \in \text{conv}(S_k) \subseteq \mathbb{C}$ is a convex combination of at most 3 points in S_k . For each k , denote each of these points by $s_k^{(i)} \in S_k$, $i = 1, 2, 3$. So $s = \sum_{i=1}^3 \alpha_k^{(i)} s_k^{(i)}$, for some $(\alpha_k^{(1)}, \alpha_k^{(2)}, \alpha_k^{(3)}) \in \Delta_{\mathbb{R}^3} = \{(\alpha_1, \alpha_2, \alpha_3) \in \mathbb{R}^3 : \sum_{p=1}^3 \alpha_p = 1, \alpha_p \geq 0\}$. Recalling that S_k is a decreasing sequence of sets, $s_k^{(i)} \in S_1$, for all k and i . Compactness of $\Delta_{\mathbb{R}^3}$ and S_1 allows us to take a subsequence $(k_n)_n$ such that $s_{k_n}^{(i)}$ and $\alpha_{k_n}^{(i)}$ are convergent subsequences to $s^{(i)}$ and $\alpha^{(i)}$, respectively. Clearly, the limit of $(\alpha_{k_n}^{(1)}, \alpha_{k_n}^{(2)}, \alpha_{k_n}^{(3)})$ belongs to the simplex, that is $(\alpha^{(1)}, \alpha^{(2)}, \alpha^{(3)}) \in \Delta_{\mathbb{R}^3}$. On the other hand, $s_{k_n}^{(i)} \in S_{k_n} \subseteq S_j$ for all $k_n \geq j$. Since the sets S_j are closed, the limit of $s_{k_n}^{(i)}$ belongs to S_j , for any $j \in \mathbb{N}$. Thus $s^{(i)} \in \bigcap_{k \geq 1} S_k$ and $s = \sum_{i=1}^3 \alpha^{(i)} s^{(i)} \in \text{conv}(\bigcap_{k \geq 1} S_k)$. □

Now we can prove our main theorem.

Theorem 3. Let $T = \bigoplus_{n \in \mathbb{N}} A_n \in \mathcal{B}(\mathcal{H})$. Then,

$$W_e(T) = \text{conv} \left(\bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(A_n)} \right).$$

Proof. We will prove that $W_e(T) = \bigcap_{k \geq 1} \text{conv} \left(\overline{\bigcup_{n \geq k} W(A_n)} \right) =: \mathcal{W}$. The theorem then follows from the previous lemma with $S_k = \overline{\bigcup_{n \geq k} W(A_n)}$.

Cantor's intersection Theorem guarantees the set \mathcal{W} is non-empty. We will start by finding an essential sequence for any $\omega \in \mathcal{W}$, thus proving that $\mathcal{W} \subseteq W_e(T)$. First, suppose that, for each $k \in \mathbb{N}$, $\omega \in \text{conv} \left(\bigcup_{n \geq k} W(A_n) \right)$. Then, there are $\omega_n^{(k)} \in W(A_n)$ and $\left(\left(\alpha_n^{(k)} \right)^2 \right)_{n \geq k} \in \Delta_{\ell^2(\mathbb{R})}$ such that

$$\omega = \sum_{n \geq k} \left(\alpha_n^{(k)} \right)^2 \omega_n^{(k)}.$$

Let $x_n^{(k)} \in \mathbb{S}_{\mathbb{C}^{\ell_n}}$ be such that $\omega_n^{(k)} = \langle A_n x_n^{(k)}, x_n^{(k)} \rangle$, for all $n \geq k$. For each k and n we denote by $\hat{x}_n^{(k)}$ the counterpart in \mathcal{H}_n of $x_n^{(k)} \in \mathbb{S}_{\mathbb{C}^{\ell_n}}$. That is, according to the notation in the introduction, $\hat{x}_n^{(k)} = \phi_n(x_n^{(k)}) \in \mathcal{H}_n$. Consider the sequence of vectors $y^{(k)} \in \mathcal{H}$ defined as follows:

$$y^{(k)} = \sum_{n \geq k} \alpha_n^{(k)} \hat{x}_n^{(k)}, \quad k \in \mathbb{N}.$$

From $\|\hat{x}_n^{(k)}\| = \|x_n^{(k)}\| = 1$ and $\hat{x}_n^{(k)} \perp \hat{x}_m^{(k)}$, for $n \neq m$, we may conclude that $\|y^{(k)}\| = 1$:

$$\|y^{(k)}\|^2 = \sum_{n \geq k} \left(\alpha_n^{(k)} \right)^2 \|\hat{x}_n^{(k)}\|^2 = \sum_{n \geq k} \left(\alpha_n^{(k)} \right)^2 = 1.$$

Let us now see that $y^{(k)} \xrightarrow[k]{0}$ by proving that $\langle y^{(k)}, z \rangle \rightarrow 0$, for any $z \in \mathcal{H}$. Write $z = \sum_{n \geq 1} z_n$, with $z_n \in \mathcal{H}_n$. We have $\|z\|^2 = \sum_{n \geq 1} \|z_n\|^2 < \infty$. Thus, there exists N such that, for $K \geq N$, the vector $z^{(K)} = \sum_{n \geq K} z_n$ has norm $\|z^{(K)}\| \leq \varepsilon$. Since $y^{(K)} \in \bigcup_{n \geq K} \mathcal{H}_n$ and $\|y^{(K)}\| = 1$ we have

$$\left| \langle y^{(K)}, z \rangle \right| = \left| \langle y^{(K)}, z^{(K)} \rangle \right| \leq \|y^{(K)}\| \|z^{(K)}\| \leq \varepsilon, \quad (2)$$

for any $z \in \mathcal{H}$. Thus $y^{(k)} \xrightarrow[k]{0}$.

Finally, since T is the block diagonal operator $T = \bigoplus_{n \in \mathbb{N}} A_n$, we have

$$\langle T \hat{x}_n^{(k)}, \hat{x}_n^{(k)} \rangle = \langle A_n x_n^{(k)}, x_n^{(k)} \rangle = \omega_n^{(k)}.$$

So it easily follows, using that $T \hat{x}_n^{(k)} \in \mathcal{H}_n$ and $\mathcal{H}_n \perp \mathcal{H}_m$ for $n \neq m$, that

$$\langle T y^{(k)}, y^{(k)} \rangle = \sum_{n \geq k} \left(\alpha_n^{(k)} \right)^2 \langle T \hat{x}_n^{(k)}, \hat{x}_n^{(k)} \rangle = \sum_{n \geq k} \left(\alpha_n^{(k)} \right)^2 \omega_n^{(k)} = \omega. \quad (3)$$

Thus $(y^{(k)})_k$ is an essential sequence for ω , that is, $\omega \in W_e(T)$.

Now suppose that, for each $k \in \mathbb{N}$, $\omega \in \text{conv} \left(\overline{\bigcup_{n \geq k} W(A_n)} \right) = \overline{\text{conv} \left(\bigcup_{n \geq k} W(A_n) \right)}$. So, there is a sequence $(\omega_m)_m \subset \text{conv} \left(\bigcup_{n \geq k} W(A_n) \right)$ converging to ω . According to the previous discussion, each element ω_m has an essential sequence $(y_m^{(k)})_k$, with unitary $y_m^{(k)} \in \bigcup_{n \geq k} \mathcal{H}_n$ and, by (3),

$\langle Ty_m^{(k)}, y_m^{(k)} \rangle = \omega_m$, for any k . Forming a sequence from the diagonal elements $(y_m^{(m)})_m$, we thus have that $\|y_m^{(m)}\| = 1$ and $\langle Ty_m^{(m)}, y_m^{(m)} \rangle = \omega_m$. Observing that $y_m^{(m)} \in \bigcup_{n \geq m} \mathcal{H}_n$, and using arguments similar to those that led to equation (2), we can conclude that $y_m^{(m)} \rightarrow 0$. Hence, $(y_m^{(m)})_m$ is an essential sequence for ω and [we have then proved that \$\omega \in W_e\(T\)\$](#) .

To prove the converse, take $\omega \in W_e(T)$ and one of its essential sequences $(y^{(m)})_m$ in $\mathbb{S}_{\mathcal{H}}$. Take arbitrary $\varepsilon > 0$ and $k \in \mathbb{N}$. Denote by P_k the projection onto $\bigcup_{n \leq k} \mathcal{H}_n$. The fact that $y^{(m)} \rightarrow 0$ implies that the projection over any finite number of coordinates converges strongly to zero, for any $k \in \mathbb{N}$, hence we must have $\|P_k y^{(m)}\| \xrightarrow{m} 0$. Together with the hypothesis that $\langle Ty^{(m)}, y^{(m)} \rangle \rightarrow \omega$, we can pick a positive integer N that simultaneously satisfies $\|P_k y^{(N)}\| < \varepsilon$ and $|\omega - \langle Ty^{(N)}, y^{(N)} \rangle| < \varepsilon$. For simplicity, we denote $y = y^{(N)}$ and $\tilde{\omega} = \langle Ty, y \rangle$. Thus, we can rewrite our previous conditions as

$$\|P_k y\| < \varepsilon \quad \text{and} \quad |\omega - \tilde{\omega}| < \varepsilon. \quad (4)$$

The strategy to show that $\omega \in \text{conv}\left(\overline{\bigcup_{n \geq k} W(A_n)}\right)$ will be to construct a convex combination $\sum_{n \geq k+1} \alpha_n \langle A_n x_n, x_n \rangle$ of elements $\langle A_n x_n, x_n \rangle \in W(A_n)$, for $n \geq k+1$. By proving that this convex combination is arbitrarily close to $\tilde{\omega}$, we prove that $\tilde{\omega}$ is arbitrarily close to $\text{conv}\left(\bigcup_{n \geq k+1} W(A_n)\right)$. But from (4), $\tilde{\omega}$ was arbitrarily close to ω and therefore this will allow us to conclude that ω is arbitrarily close to $\text{conv}\left(\bigcup_{n \geq k+1} W(A_n)\right)$. That is, $\omega \in \text{conv}\left(\bigcup_{n \geq k+1} W(A_n)\right) = \text{conv}\left(\overline{\bigcup_{n \geq k+1} W(A_n)}\right)$. Since this is true for each $k \in \mathbb{N}$, we have

$$\omega \in \bigcap_{k \geq 1} \text{conv}\left(\overline{\bigcup_{n \geq k} W(A_n)}\right) = \mathcal{W}.$$

To construct the referred convex combination $\sum_{n \geq k+1} \alpha_n \langle A_n x_n, x_n \rangle$, recall that $y = y^{(N)}$ and write $y = (y_n)_n \in \mathcal{H}$, with $y_n \in \mathcal{H}_n$. Let $\hat{x}_n \in \mathcal{H}_n$ be the [unit](#) vectors with the same direction of that of $y_n \in \mathcal{H}_n$, that is, $\|y_n\| \hat{x}_n = y_n$. Denote $x_n = \phi_n^{-1}(\hat{x}_n) \in \mathbb{C}^{\ell_n}$, for $n \geq k$, and $\beta = \frac{1}{\|(I-P_k)y\|^2}$. Note that $1 = \|y\|^2 = \|P_k y\|^2 + \|(I-P_k)y\|^2$ and recall from (4) that $\|P_k y\|^2 < \varepsilon^2$. Hence, $\|(I-P_k)y\|^2 > 1 - \varepsilon^2 > 0$ if we pick ε small enough.

Let $\alpha_n = \frac{\|y_n\|^2}{\|(I-P_k)y\|^2} \geq 0$. Since $\sum_{n \geq k+1} \|y_n\|^2 = \|(I-P_k)y\|^2$ then $\sum_{n \geq k+1} \alpha_n = 1$. We thus obtain

$$\sum_{n \geq k+1} \alpha_n \langle A_n x_n, x_n \rangle = \sum_{n \geq k+1} \alpha_n \langle T_n \hat{x}_n, \hat{x}_n \rangle = \beta \sum_{n \geq k+1} \langle T_n y_n, y_n \rangle = \beta \left(\tilde{\omega} - \sum_{n \leq k} \langle T_n y_n, y_n \rangle \right).$$

Using (4) again, we have $\|P_k y\|^2 = 1 - \|(I - P_k)y\|^2 < \varepsilon^2$ and $\beta - 1 < \frac{1}{1 - \varepsilon^2} - 1 = \frac{\varepsilon^2}{1 - \varepsilon^2}$. Hence,

$$\begin{aligned} \left| \sum_{n \geq k+1} \alpha_n \langle A_n x_n, x_n \rangle - \tilde{\omega} \right| &= \left| \beta(\tilde{\omega} - \sum_{n \leq k} \langle T_n y_n, y_n \rangle) - \tilde{\omega} \right| \\ &\leq (\beta - 1) |\tilde{\omega}| + \beta \left| \sum_{n \leq k} \langle T_n y_n, y_n \rangle \right| \\ &< \frac{\varepsilon^2}{1 - \varepsilon^2} |\tilde{\omega}| + \beta |\langle T(P_k y), P_k y \rangle| \\ &< \frac{\varepsilon^2}{1 - \varepsilon^2} |\tilde{\omega}| + \beta \|T\| \varepsilon^2. \end{aligned}$$

We have just proved that for any k the convex combination $\sum_{n \geq k+1} \alpha_n \langle A_n x_n, x_n \rangle$ is arbitrarily close to $\tilde{\omega}$, as intended. \square

Here are two simple applications of the above result.

Example 4. If $T = \bigoplus_{n \in \mathbb{N}} A_n \in \mathcal{B}(\mathcal{H})$, with $A_n = [\lambda_n] \in \mathcal{M}_{1 \times 1}(\mathbb{C})$, for all $n \in \mathbb{N}$, then T is a diagonal operator. Recall from our discussion in the introduction the definition of closed limit superior of a sequence of sets. Theorem 3 says that

$$W_e(T) = \text{conv} \left(\bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} \{\lambda_n\}} \right) = \text{conv} \left(\overline{\lim} \{\lambda_n\} \right).$$

Example 5. Let $T = \bigoplus_{n \in \mathbb{N}} A_n \in \mathcal{B}(\mathcal{H})$, with $A_n = A$, for all $n \in \mathbb{N}$. Then, applying Theorem 3 and the fact that $W(A)$ is convex and closed, we find that

$$W_e(T) = \text{conv} \left(\bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(A)} \right) = W(A).$$

Theorem 3 gives us a way to find the essential numerical range of $T = \bigoplus_n A_n$ for any block decomposition $(A_n)_n$ of T . As previously stated, the block operator decomposition is not unique and for a particular decomposition, judiciously chosen, the result can be further simplified. We can find a way to decompose the operator T as $T = \bigoplus_n A_n$ so that the convex hull can be dismissed in the formula in Theorem 3. The relevance of the next proposition in terms of practical calculations is reduced. In fact, it is harder to explicitly describe the decomposition constructed therein than it is to directly use the result from the preceding theorem. However, theoretically, it may be useful to have such result at hand. A formulation close to the one in our proposition is used in ([A]). Nevertheless, besides containing an inaccuracy in the positioning of the closure, there is no reference to the fact that it holds true only for some decompositions of T . Also, the result is stated without a proof.

The next proposition proves rigorously the existence of a particular decomposition where the essential numerical range can be described without the convexification, but before that we need two preparing [lemmas](#). The first of these lemmas states that the proposition is invariant under translations.

Lemma 6. *Let $z \in \mathbb{C}$ and let $T = \bigoplus A_n \in \mathcal{B}(\mathcal{H})$ be a block diagonal operator.*

$$W_e(T) = \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(A_n)} \quad \text{if and only if} \quad W_e(T - zI) = \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(A_n - zI)}.$$

Proof. We start by noting that if T is the block diagonal operator with decomposition $T = \bigoplus A_n$ then $T - zI$ is also a block diagonal operator with decomposition $\bigoplus A_n - zI = \bigoplus (A_n - zI)$.

Since $W_e(T - zI) = W_e(T) - z$ and $W(A_n) = W(A_n - zI) + z$, if

$$W_e(T) = \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(A_n)},$$

we have that

$$W_e(T - zI) = W_e(T) - zI = \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(A_n) - zI} = \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(A_n - zI)}.$$

The other implication follows from the previous one, considering $\tilde{T} = T + zI$. \square

On a convex set $A \subset \mathbb{C}$ a point $a \in A$ is an extreme point if it is not a convex combination of any other points in the set A . That is, we say that a is an extreme point of A if when $a, b, c \in A$ and $a = \alpha b + (1 - \alpha)c$, for some $\alpha \in [0, 1]$, then $b = c = a$. We denote by $\mathcal{E}(T)$ the set of extreme points of $W_e(T)$. Since $W_e(T)$ is compact and convex, Krein-Milman's Theorem asserts that $W_e(T) = \text{conv}(\mathcal{E}(T))$.

On the other hand, for any $\omega \in \mathbb{C} \setminus \{0\}$ we can write uniquely $\omega = |\omega|e^{i\theta}$, for some $\theta \in [0, 2\pi)$. Thus we can define an angle function $\theta : \mathbb{C} \setminus \{0\} \rightarrow [0, 2\pi)$. Denote $\theta|_A$ the restriction of the function θ to the set A . Next lemma shows that we can find a translation $T - zI$ of the operator T where $\theta|_{\mathcal{E}(T - zI)}$, the restricted angle function to the set of extreme points $\mathcal{E}(T - zI)$, is injective. That is, if we apply an adequate translation there are no two extreme points of $\mathcal{E}(T - zI)$ with the same angle.

Lemma 7. *Let $T \in \mathcal{B}(\mathcal{H})$. There exists $z \in \mathbb{C}$ such that $\theta|_{\mathcal{E}(T - zI)}$ is injective.*

Proof. In the case the essential numerical range of T is a singleton, $W_e(T) = \{a\} = \mathcal{E}(T)$, there are two possibilities: either $a \neq 0$ and then $\theta|_{\mathcal{E}(T)}$ is trivially injective, or $a = 0$, in which case $W_e(T - zI) = \{-z\} = \mathcal{E}(T - zI)$, for any $z \in \mathbb{C} \setminus \{0\}$, and hence again $\theta|_{\mathcal{E}(T - zI)}$ is trivially injective.

Otherwise, if $W_e(T)$ is not a singleton, the set of extreme points $\mathcal{E}(T)$ has at least two elements, $\omega_1, \omega_2 \in \mathcal{E}(T)$. We can choose $z \in \text{conv}\{\omega_1, \omega_2\} \subseteq W_e(T)$, with $z \notin \{0, \omega_1, \omega_2\}$, and translate $W_e(T)$ by z . It is clear that $0 \in W_e(T - zI) \setminus \mathcal{E}(T - zI)$, since z was an element in $W_e(T)$ and not in $\mathcal{E}(T)$. Thus the function $\theta|_{\mathcal{E}(T - zI)}$ is well-defined since 0 is not in its domain. On the other hand, injectivity of $\theta|_{\mathcal{E}(T - zI)}$ is a consequence of $W_e(T - zI)$ being convex; if $\theta(z_1) = \theta(z_2)$, for some $z_1, z_2 \in \mathcal{E}(T - zI)$ with $|z_1| < |z_2|$, z_1 would be a convex combination of $0 \in W_e(T - zI)$ and $z_2 \in W_e(T - zI)$, thus not an extreme point of $W_e(T - zI)$. \square

Proposition 8. Let $T = \bigoplus_n A_n$ be a block diagonal operator. Then, there is a decomposition for which $T = \bigoplus_n \tilde{A}_n$ and

$$W_e(T) = \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W(\tilde{A}_n)}. \quad (5)$$

Proof. Lemma 7 assures the existence of $z \in \mathbb{C}$ such that $\theta|_{\mathcal{E}(T-zI)}$ is injective. If we prove (5) for $W_e(T-zI)$, from Lemma 6 this result holds true for $W_e(T)$. Therefore, we can assume without loss of generality that T is such that $\theta|_{\mathcal{E}(T)}$ is injective.

In order to simplify notation, write $W_n = W(A_n)$, $\tilde{W}_n = W(\tilde{A}_n)$, $W_e = W_e(T)$ and $\mathcal{E} = \mathcal{E}(T)$. First, observe that for any decomposition of T we have

$$\mathcal{E} \subset \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W_n}. \quad (6)$$

This follows from Theorem 3, which asserts that $W_e = \text{conv}\left(\bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} W_n}\right)$ and by definition of extreme point.

Moreover, note that if ω_e is a point in $\overline{\bigcup_{n \geq k} W_n}$, for all $k \in \mathbb{N}$, then for any $\zeta > 0$ there is a $\gamma_{n_k} \in W_{n_k}$, with $n_k \geq k$, such that $|\gamma_{n_k} - \omega_e| < \zeta$. Hence, an extreme point ω_e of W_e has the following property:

$$\text{for any } \zeta > 0 \text{ there is a sequence } (n_k)_k, \text{ with } n_k \geq k, \text{ such that } d(\omega_e, W_{n_k}) < \zeta. \quad (7)$$

Consider an arbitrary $\varepsilon > 0$. We next construct a decomposition $(\tilde{A}_m)_m$ of the operator T for which the result holds.

When $m = 1$ pick one element $\omega_e \in \mathcal{E}$. In view of (7), take M_1 to be such that $d(\omega_e, W_{M_1}) < \varepsilon$ and let $\tilde{A}_1 = \bigoplus_{p=1}^{M_1} A_p$.

For $m \geq 2$, we start by dividing the interval $[0, 2\pi)$ into m subintervals $2\pi [j/m, (j+1)/m)$, for $j = 0, \dots, m-1$. If $\theta(\mathcal{E}) \cap 2\pi [j/m, (j+1)/m) \neq \emptyset$, pick any $\omega_e \in \mathcal{E}$ such that $\theta(\omega_e) \in 2\pi [j/m, (j+1)/m)$. Denote such point by $\omega_j^{(m)}$. For those pairs (m, j) with

$$\theta(\mathcal{E}) \cap 2\pi \left[\frac{j}{m}, \frac{j+1}{m} \right) = \emptyset,$$

we let $\omega_j^{(m)} = \omega_{j'}^{(m)}$, where $j' \in \{0, \dots, m-1\}$ such that $\theta(\mathcal{E}) \cap 2\pi \left[\frac{j'}{m}, \frac{j'+1}{m} \right) \neq \emptyset$. According to (7), for each of these m points $\omega_j^{(m)}$ in \mathcal{E} there is an integer $m_j \geq M_{m-1} + 1$ such that $d(\omega_j^{(m)}, W_{m_j}) < \varepsilon/m$. Let $M_m = \max_{0 \leq j \leq m-1} m_j$ and define

$$\tilde{A}_m = \bigoplus_{p=M_{m-1}+1}^{M_m} A_p.$$

Since $M_m > M_{m-1}$, we have that $M_m \xrightarrow{m} +\infty$ and it is clear that T is the direct sum of the operators \tilde{A}_m .

Claim: the decomposition (\tilde{A}_m) satisfies (5). We start by proving the inclusion $W_e \subset \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} \tilde{W}_n}$. Recall that $\tilde{W}_m = W(\tilde{A}_m)$. So, for each $m \geq 1$,

$$\tilde{W}_m = W \left(\bigoplus_{p=M_{m-1}+1}^{M_m} A_p \right) = \text{conv} \left(\bigcup_{p=M_{m-1}+1}^{M_m} W_p \right).$$

Since $d(\omega_j^{(m)}, W_{m_j}) < \varepsilon/m$ and $M_{m-1} < m_j \leq M_m$, for all $j = 0, \dots, m$, then

$$d(\omega_j^{(m)}, \tilde{W}_m) \leq d(\omega_j^{(m)}, W_{m_j}) < \varepsilon/m. \quad (8)$$

Let $\omega_e \in \mathcal{E}$. For any m , there is $j \in \{0, \dots, m-1\}$ such that $\theta(\omega_e) \in 2\pi[j/m, (j+1)/m)$. Then, the corresponding $\omega_j^{(m)}$, whose angle $\theta(\omega_j^{(m)})$ belongs to the same interval, satisfies $|\theta(\omega_e) - \theta(\omega_j^{(m)})| < 2\pi/m$. Denote such $\omega_j^{(m)}$ by γ_m . We thus obtain a sequence $(\gamma_m)_m$ such that $\theta(\gamma_m) \rightarrow \theta(\omega_e)$. Since $\gamma_m, \omega_e \in \mathcal{E}$ and $\theta(\gamma_m) \rightarrow \theta(\omega_e)$, by injectivity of θ in \mathcal{E} , we have $\gamma_m \rightarrow \omega_e$. So, for any $\delta > 0$, we can pick $M \in \mathbb{N}$ such that, for $N \geq M$, $d(\gamma_N, \omega_e) < \delta/2$ and $d(\gamma_N, \tilde{W}_N) < \varepsilon/N < \delta/2$ (see (8)), which implies that

$$d(\omega_e, \tilde{W}_N) \leq d(\omega_e, \gamma_N) + d(\gamma_N, \tilde{W}_N) < \delta. \quad (9)$$

Hence, we have $\mathcal{E} \subseteq \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} \tilde{W}_n}$.

We now claim that $\text{conv}(\mathcal{E}) \subset \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} \tilde{W}_n}$. If $\omega \in \text{conv}(\mathcal{E})$ there are $\omega_e^i \in \mathcal{E}$, for $i = 1, 2, 3$, such that $\omega = \sum_i \alpha_i \omega_e^i$, for some $(\alpha_1, \alpha_2, \alpha_3) \in \Delta_{\mathbb{R}^3}$. From (9), we know that for any $\delta > 0$, there is M_i such that $d(\omega_e^i, \tilde{W}_N) < \delta$ for $N \geq M_i$. Then, for $N \geq \max\{M_1, M_2, M_3\}$ it follows that

$$d(\omega, \tilde{W}_N) = d\left(\sum_i \alpha_i \omega_e^i, \tilde{W}_N\right) \leq \sum_i \alpha_i d(\omega_e^i, \tilde{W}_N) < \delta,$$

using the fact that the set \tilde{W}_N is convex and so the function $d(\cdot, \tilde{W}_N)$ is convex. Therefore, for each $k \in \mathbb{N}$, there is $N \geq k$ such that $d(\omega, \tilde{W}_N) < \delta$. It follows that $d(\omega, \bigcup_{n \geq k} \tilde{W}_n) < \delta$. Since δ was arbitrary, we conclude that $\omega \in \overline{\bigcup_{n \geq k} \tilde{W}_n}$, for the given k . That is, $\omega \in \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} \tilde{W}_n}$ and so

$$W_e = \text{conv}(\mathcal{E}) \subset \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} \tilde{W}_n}.$$

Now, since Theorem 3 is valid for any decomposition, we have

$$\text{conv}(\mathcal{E}) = W_e = \bigcap_{k \geq 1} \text{conv} \left(\overline{\bigcup_{n \geq k} \tilde{W}_n} \right) \supset \bigcap_{k \geq 1} \overline{\bigcup_{n \geq k} \tilde{W}_n}.$$

The result then follows. \square

The next example elucidates that to find explicitly a decomposition as in Proposition 8 can be tricky. However, Theorem 3 makes possible to easily compute the essential numerical range.

Example 9. Let $\varphi : \mathbb{N} \rightarrow \mathbb{Q} \cap [0, 2\pi]$ be any bijection and $\Theta : [0, 2\pi] \rightarrow \mathbb{S}_{\mathbb{C}}$ the map defined by $\Theta(\theta) = e^{i\theta}$. Note that Θ is continuous and bijective. Now, define the composite map

$$\phi = \Theta \circ \varphi : \mathbb{N} \rightarrow \mathbb{S}_{\mathbb{C}}, \phi(n) = e^{i\varphi(n)}.$$

Then, ϕ is also bijective. Define the bounded block diagonal operator $T = \text{diag}\{\phi(n)\} = \bigoplus A_n$ with $A_n = [\phi(n)]$, for each $n \in \mathbb{N}$. As seen in [Example 4](#),

$$W_e(T) = \text{conv}\left(\overline{\lim}\{\phi(n)\}_n\right).$$

Since $\overline{\lim}\{\phi(n)\}_n = \mathbb{S}_{\mathbb{C}}$ and $W_e(T)$ is convex, we conclude that $W_e(T) = \{x \in \mathbb{C} : \|x\| \leq 1\}$ is the closed unit disc.

REFERENCES

- [A] Allen, G. D., and J. D. Ward. *A simultaneous lifting theorem for block diagonal operators*. Transactions of the American Mathematical Society, **250**, 1979, pp. 385–97.
- [FSW] P. A. Filmore, J. G. Stampfli, J. P. Williams, *On the essential numerical range, the essential spectrum and a problem of Halmos*, Acta. Sci. Math (Szeged) **33** (1973), 172–192.

LUÍS CARVALHO, ISCTE - LISBON UNIVERSITY INSTITUTE, AV. DAS FORÇAS ARMADAS, 1649-026, LISBON, PORTUGAL, AND CENTER FOR MATHEMATICAL ANALYSIS, GEOMETRY, AND DYNAMICAL SYSTEMS, MATHEMATICS DEPARTMENT, INSTITUTO SUPERIOR TÉCNICO, UNIVERSIDADE DE LISBOA, AV. ROVISCO PAIS, 1049-001 LISBOA, PORTUGAL

Email address: luis.carvalho@iscte-iul.pt

CRISTINA DIOGO, ISCTE - LISBON UNIVERSITY INSTITUTE, AV. DAS FORÇAS ARMADAS, 1649-026, LISBON, PORTUGAL, AND CENTER FOR MATHEMATICAL ANALYSIS, GEOMETRY, AND DYNAMICAL SYSTEMS, MATHEMATICS DEPARTMENT, INSTITUTO SUPERIOR TÉCNICO, UNIVERSIDADE DE LISBOA, AV. ROVISCO PAIS, 1049-001 LISBOA, PORTUGAL

Email address: cristina.diogo@iscte-iul.pt

SÉRGIO MENDES, ISCTE - LISBON UNIVERSITY INSTITUTE, AV. DAS FORÇAS ARMADAS, 1649-026, LISBON, PORTUGAL, AND CENTRO DE MATEMÁTICA E APLICAÇÕES, UNIVERSIDADE DA BEIRA INTERIOR, RUA MARQUÊS D'ÁVILA E BOLAMA, 6201-001, COVILHÃ

Email address: sergio.mendes@iscte-iul.pt

HELENA SOARES, ISCTE - LISBON UNIVERSITY INSTITUTE, AV. DAS FORÇAS ARMADAS, 1649-026, LISBON, PORTUGAL, AND CENTRO DE INVESTIGAÇÃO EM MATEMÁTICA E APLICAÇÕES, UNIVERSIDADE DE ÉVORA, COLÉGIO LUÍS ANTÓNIO VERNEY, RUA ROMÃO RAMALHO, 59, 7000-671 ÉVORA, PORTUGAL

Email address: helen.a.soares@iscte-iul.pt